

# 1-dimensionale Burgersgleichung

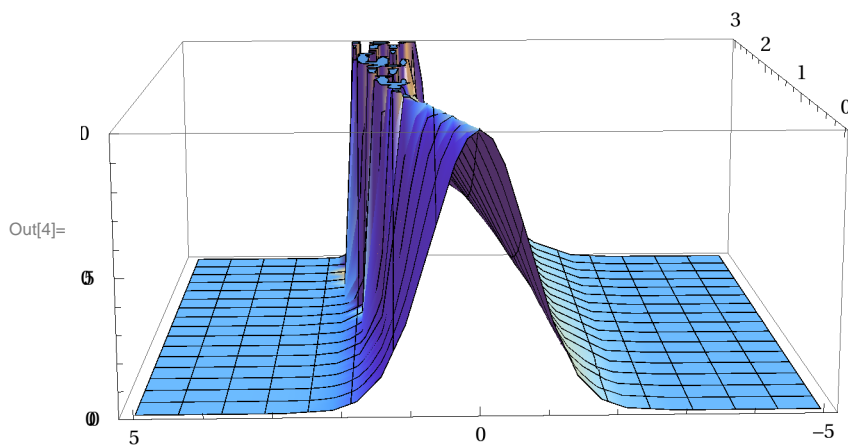
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## Numerisch ohne Viskosität:

```
In[3]:= NDSolve[{D[v[t, x], t] == -v[t, x] D[v[t, x], x],  
  v[0, x] == Exp[-x^2], v[t, -5] == Exp[-5^2], v[t, 5] == Exp[-5^2]}, v,  
  {t, 0, 3}, {x, -5, 5}, Method -> {"MethodOfLines", "SpatialDiscretization" ->  
  {"TensorProductGrid", MaxPoints -> 1 000 000, StartingPoints -> 1 000 000}}]
```

```
Out[3]= {{v -> InterpolatingFunction[{{0., 3.}, {-5., 5.}}, <>]}}
```

```
In[4]:= Plot3D[Evaluate[v[t, x] /. %], {t, 0, 3}, {x, -5, 5}, PlotRange -> {0, 1}]
```



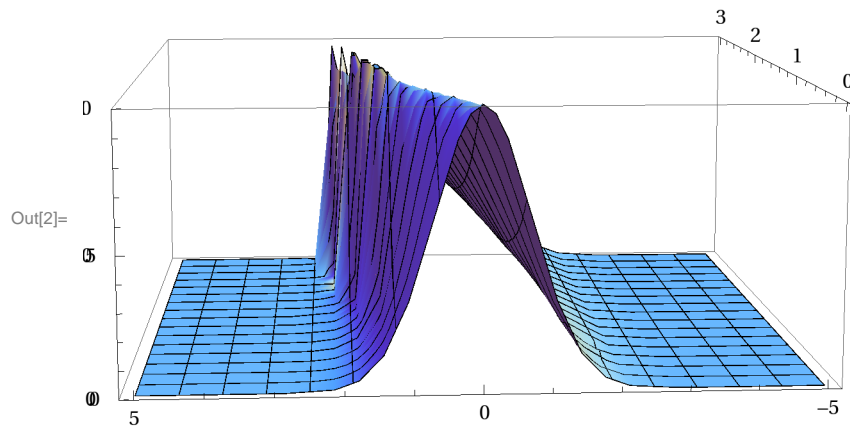
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## Numerisch mit Viskosität:

```
In[1]:= NDSolve[{D[v[t, x], t] == -v[t, x] D[v[t, x], x] + 0.01 D[v[t, x], x, x],  
  v[0, x] == Exp[-x^2], v[t, -5] == Exp[-5^2], v[t, 5] == Exp[-5^2]}, v,  
  {t, 0, 3}, {x, -5, 5}, Method -> {"MethodOfLines", "SpatialDiscretization" ->  
  {"TensorProductGrid", MaxPoints -> 1 000 000, StartingPoints -> 1 000 000}}]
```

```
Out[1]= {{v -> InterpolatingFunction[{{0., 3.}, {-5., 5.}}, <>]}}
```

```
In[2]:= Plot3D[Evaluate[v[t, x] /. %], {t, 0, 3}, {x, 5, -5}, PlotRange -> {0, 1}]
```




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### Exakt ohne Viskosität:

```
In[8]:= ParametricPlot3D[{x + t Exp[-x^2], t, Exp[-x^2]}, {x, -5, 5}, {t, 0, 3}, AspectRatio -> 1]
```

